١	Satellite-based prediction of surface dust mass concentration in southeastern
۲	Iran using gradient boosting regression
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۲٤ Abstract

۲0 The southeastern section of Iran, especially the province of Khuzestan, experience ۲٦ severe air pollution levels, such as high values of Surface Dust Mass Concentration (SDMC). The province lacks accurate and well-placed ground observational ۲۷ stations, therefore the only viable approach for evaluating SDMC is via remote ۲۸ sensing. In this study, meteorological, hydrological and geological data on 11 input ۲٩ ۳. variables from Modern-Era Retrospective analysis for Research and Applications ۳١ Version (MERRA-2), Global Precipitation Measurement (GPM) and Global Land Data Assimilation System (GLDAS) for the year 2018 are used for prediction of the ٣٢ ٣٣ SDMC values, also obtained from MERRA-2. For real-time prediction, Pearson's Correlation Coefficient (PCC) analysis shows that wind-related variables – surface ٣٤ wind speed, surface aerodynamic conductivity and surface pressure – are those with ۳0 the highest correlation with SDMC. Using the Gradient Boosting Regression (GBR) ٣٦ algorithm, these three variables can simulate SDMC with good accuracy (CC =۳۷ 0.815, N - RMSE = 0.605). Future forecasting of SDMC requires knowledge of ۳۸ both wind-related and heat-related variables. However, SDMC predictions can be ۳٩ obtained with the GBR algorithm with adequate accuracy (CC = 0.640. NRMSE = ٤٠ 0.781) by just considering the surface pressure value observed four days before the ٤١ forecasted day. This study shows that robust predictions of SDMC can be obtained ٤٢ using exclusively remote sensing data, without ground-based observations. ٤٣

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Keywords: Surface dust mass concentration, Gradient Boosting Regression,
 Prediction, Khuzestan

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• 1. Introduction

Recent reports by the World Health Organization (WHO) revealed that nearly seven ٥٢ million people die in the world due to high levels of air pollution every year (WHO, ٥٣ 2014). Major air pollutants are carbon monoxide, sulfur, nitrogen dioxide, and 0 2 surface-level ozone (Chen et al., 2007, Council, 1992, Duan et al., 2019, Sunyer et 00 al., 2003). Particulate Matter (PM) is also highlighted by WHO as the thirteenth ٥٦ ٥٧ mortality cause around the world, which makes it further hazardous (Anderson et al., 2012). PM is a mixture of microscopic particles and liquid substances such as ٥٨ metals, organic materials, acids and dust (Planning, 1996, USEPA, 2019). PM can 09 cause significant health problems, such as blood pressure, lung cancer, and ٦. cardiovascular diseases (Brook & Rajagopalan, 2009, Hamanaka & Mutlu, 2018, ٦1 Raaschou-Nielsen et al., 2016), therefore monitoring its concentration is critical for ٦٢ health and environmental purposes. ٦٣

Numerous studies have been conducted on PM concentration measurement, using various sampling approaches and instruments (Amaral *et al.*, 2015, Kwasny *et al.*, 2010, Nakata *et al.*, 2013). Ground-based measurement, mostly done with monitoring stations, is the most commonly employed method. However, while the direct sampling approach is considered as the most accurate, it is neither cost- nor time-efficient, and station numbers are typically limited and station spatial distribution in generally irregular (M. Lee *et al.*, 2016, D. Liu & Li, 2015).

Recently, to overcome the disadvantages of direct sampling, Remote Sensing (RS)
methods have become increasingly utilized for forecasting of hydrological and
meteorological phenomena (Asadollah *et al.*, 2021, Ghozat *et al.*, 2022, Shiru *et al.*,
2022). RS covers a wide range of spatial and temporal data observations that can
particularly benefit regions that lack direct observation stations (Campbell &
Wynne, 2011, Davis & Swain, 1978), as in the case of Iran. To the authors'

knowledge, there are no useful historical ground-based datasets regarding the
 concentration of air pollutants in any province of Iran.

٧٩ Early satellite versions were unable to record near-surface PM concentration and instead provided a substitute parameter called Aerosol Optical Depth or AOD (Diao ٨٠ et al., 2019). Considering a ray of light being radiated from a satellite source, the ۸١ AOD is defined as the decay level of that light reflection from the surface, which is ٨٢ ٨٣ mainly caused by the presence of particles in the air column (Van Donkelaar et al., 2010). The Multi-Angle Implementation of Atmospheric Correction (MAIAC) ٨٤ method, used in conjunction with the satellite-based sensor Moderate Resolution ٨0 Imaging Spectroradiometer (MODIS), is widely used for predicting the AOD over ٨٦ different regions around the globe. (A. Chudnovsky et al., 2013) evaluated the ٨٧ applicability of the MAIAC algorithm by comparing its predictions with ground- $\lambda\lambda$ based PM2.5 observations from 84 monitoring stations across New England in the ٨٩ ۹. United States over the period 2002-2008. The results indicated that the AOD ۹١ obtained from the MAIAC is correlated with the observed PM2.5 surface ٩٢ concentration. This research also showed that the MAIAC-AOD shows a better correlation with the in-situ PM2.5 compared to conventional MODIS-AQUA ٩٣ ٩٤ products.

Several studies focused on finding the relation between the AOD and ground-level 90 97 PM concentration. (H. J. Lee et al., 2012) developed a statistical method to predict the concentration of daily PM2.5 by combining the satellite AOD data with the ٩٧ ground-based ones. Specifically, the MODIS satellite outputs were used together ٩٨ 99 with the observed data from the U.S. Environmental Protection Agency (EPA). The authors evaluated two groups of days consisting of days with or without satellite data 1 . . availability during the period 2000-2008 for the New England. With a Pearson's 1.1 Correlation Coefficient (PCC) of 0.91, their predictions were showed this to be a ۱۰۲

suitable approach, especially in urban areas. (A. A. Chudnovsky et al., 2014) 1.5 predicted the Fine Particulate Matter (FPM) in the air using high-resolution aerosol 1.5 data obtained with the MAIAC algorithm using MODIS satellite observations. 1.0 Several meteorological parameters (e.g., speed of wind and relative humidity), as 1.7 well as the land use, were utilized to predict the daily-based FPM over New England. ۱.۷ After calibrating the FPM satellite data with ground-based observation originated ۱.۸ 1.9 from the EPA, they used a novel interpolation approach, the Inverse Probability 11. Weighting (IPW), to complete the prediction task. Their proposed model predicted real-time FPM with high accuracy. Analogously, (Just et al., 2015) used the MODIS 111 ۱۱۲ daily AOD values to predict PM2.5 over Mexico City from 2004 to 2014 using statistical modeling. With a correlation coefficient R value of 0.85, their model 117 proved to be an accurate tool for predicting PM2.5 concentration an subcategory of 115 AOD. (X. Zhang et al., 2018) employed the MAIAC-MODIS satellite outputs to 110 117 extract the AOD records and developed a multi-input statistical model based on 117 geographical properties, climate variables (air temperature, wind speed, and visibility), and land use data to predict the ground-measured PM2.5 concentrations 114 ۱۱۹ over Texas in the United States, between the years 2008 and 2013. Their proposed model provided accurate predictions with a correlation coefficient of 0.79~0.83. ۱۲.

In the last decade, technological advancement has led Artificial Intelligence (AI) to 171 become the dominant regression and classification approach in many research fields ۱۲۲ (Mehdizadeh et al., 2017, Nourani et al., 2014, W.-C. Wang et al., 2009). Compared ۱۲۳ to statistical and numerical methods, AI can achieve the desired target in a much 175 faster and easier manner (Al-Othman et al., 2022, Karandish & Šimůnek, 2016). 170 Benchmark AI algorithms such as Artificial Neural Network (ANN) and Adaptive 177 ۱۲۷ Neuro-Fuzzy Inference System (ANFIS) have been widely used for prediction in earth sciences. (Mirzaei et al., 2019) investigated the relationship between the ۱۲۸

satellite-originated AOD values and ground measured PM2.5 concentrations over
 Tehran in Iran. A model known as Geographically and Temporally Weighted
 Regression (GTWR) was used to assess this relationship between the years of 2011
 and 2017 and convert MODIS-AOD values to PM2.5 surface concentrations.
 Comparison of four different AI algorithms reveal that the Generalized Regression
 Neural Network (GRNN) algorithm performed better than its alternatives, ANN and
 ANFIS.

١٣٦ More advanced AI methods, based on Machine Learning (ML), generally provide better prediction performance compared to "classic" AI algorithms. The MLs show ۱۳۷ better task in reducing the prediction associated bias and variances, have better ۱۳۸ ۱۳۹ overfitting-elusive procedures and can be manually tuned more easily (Khanzode & Sarode, 2020, Müller & Guido, 2016, Wuest et al., 2016). While the early ML ١٤. models, such as Support Vector Machine (SVM) and Multivariate Adaptive 121 ١٤٢ Regression Splines (MARS) demonstrated acceptable performance, newer models 157 called ensemble algorithms have shown superior applicability. Ensemble algorithms ١٤٤ such as Ada-boost, Random Forest (RF), and Extreme Tree Regression (ETR) were successfully applied in various studies, outperforming the classic AI algorithms (F. 120 Wang et al., 2021, J. Zhang et al., 2019, Zhu et al., 2021). 127

The literature review by (Chu et al., 2016) shows that multiple studies have adopted ١٤٧ ١٤٨ AI algorithms to predict aerosol levels over different regions of the world. For example, (Di et al., 2016) predicted the AOD over the Unites States using ANN 129 algorithms. (Nguyen et al., 2015) employed Support Vector Regression (SVR) and 10. Multiple linear regression (MLR) to simulate the organic carbon concentrations in 101 Gosan, South Korea, between the years 2011 and 2012. Another related study (Lary 101 107 et al., 2014) utilized a machine learning regression to predict the worldwide aerosol concentration from 1997 to 2014. (Nabavi et al., 2018) compared the performance 102

of several ML algorithms for the prediction of monthly AOD in the western region 100 107 of Asia using the MODIS outputs. They used wind characteristics, soil temperature, 101 rainfall, drought index, and several other parameters as ML initial predictors, while the MODIS AOD value was used as the target variable. (Kianian et al., 2021) 101 109 employed RF as an ensemble ML algorithm to predict the spatial distribution of PM2.5, especially in regions that are prone to gaps in AOD coverage. They also used 17. 171 a statistical approach known as Lattice Kriging. Like many previous studies, they ١٦٢ first calibrated the MODIS outputs with the EPA ground-based observations. Surface pressure, wind components, temperature, rainfall, relative humidity, ١٦٣ 175 radiation flux and many other variables were investigated as the meteorological parameters for PM2.5 prediction. 170

177 While the majority of the previous studies used the AOD data obtained from the MODIS satellite, few have investigated other satellite-based aerosol diagnosis 177 ۱٦٨ outputs such as those from the Modern-Era Retrospective analysis for Research and 179 Applications Version 2, known as MERRA-2 (Gelaro *et al.*, 2017). (Sun *et al.*, 2019) compared the AOD outputs from MERRA-2 and MODIS and evaluated them ۱۷. against ground-based observations at 12 stations in China. Their findings suggested 171 ۱۷۲ that the MERRA-2 outputs are in good agreement with both MODIS-based and ground-based values. (Gueymard & Yang, 2020) focused on global AOD data for a ۱۷۳ period of 15 years and showed that MERRA-2 performs better than the European 175 140 Centre for Medium-Range Weather Forecasts (ECMWF)'s Copernicus Atmosphere Monitoring Service (CAMS). Besides AOD diagnosis outputs, MERRA-2 provides ۱۷٦ 177 data on ambient air pollutants such as sulfate and dust concentration at the surface level. ۱۷۸

This study focuses on surface dust, which is one of the main PM components, and aims to forecast the Surface Dust Mass Concentration (SDMC). The dust-related

output of MERRA-2 was selected as the target parameter in this study, as done in ۱۸۱ ۱۸۲ several other studies too (Ukhov et al., 2020, Veselovskii et al., 2018, Xu et al., 2020, Yao et al., 2020). The Gradient Boosting Regression (GBR) was used here, ۱۸۳ because it is a robust and effective ensemble-based prediction algorithm (Johnson et ۱۸٤ al., 2018, Srivastava et al., 2018, Y. Zhang & Haghani, 2015). Differently from 110 previous investigations, this study uses exclusively remote sensing data for dust ۱۸٦ ۱۸۷ concentration prediction. This study also presents, for the first time, a comprehensive analysis of correlation between various meteorological, hydrological, and geological ۱۸۸ variables with SDMC, and successfully forecasts SDMC few days in advance. ۱۸۹

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2. Materials and Methods

2.1. Study Area

198 Dust bowl-like storms have a significant socio-environmental impact in Iran (Salami 195 et al., 2021). Several studies investigated short- and long-term AOD patterns over Iran (Arkian & Nicholson, 2018, Sabetghadam et al., 2018, Salami et al., 2021, 190 Yousefi et al., 2020). Nearly all these studies pinpoint the province of Khuzestan as ۱۹٦ the region with the highest dust concentration. For example, (Rezaei et al., 2019) ۱۹۷ evaluated Iran based on its spatial and temporal dust aerosol patterns utilizing the 191 199 MODIS outputs between 2006 to 2015. Their results show that the Khuzestan and ۲.. Sistan provinces are the most affected provinces among others. Similar results were obtained by (Mirakbari & Ebrahimi Khusfi, 2020) and (Dadashi-Roudbari & ۲.۱ Ahmadi, 2020), which makes the Khuzestan province a good case study for ۲.۲ evaluating the SDMC. ۲.۳

As shown in Figure 1, the Khuzestan province is located in the southwestern region of Iran. It has an approximate area of 63,000 km² and 4 million inhabitants. Based

on the digital elevation map in Figure 1, Khuzestan's elevation below and above the ۲.٦ ۲۰۷ sea level ranges between -105 and 3741 meters, respectively. This is associated with ۲۰۸ great diversity in climate conditions, from the cold temperatures in the north to tropical conditions in the south. Khuzestan's summer months are considered those ۲.٩ from April to September, while October to March are the winter months. The annual ۲١. average maximum and minimum temperature of this province are $50^{\circ}C$ and $9^{\circ}C$ in 111 ۲۱۲ July and March, respectively. The annual precipitation rate varies from $\sim 200 mm$ (sea coast in the south) to $\sim 1050 \text{ mm}$ (near the Zagros mountains in the north). The 212 ۲۱٤ dominant wind direction in this province is from west to east and northwest to southeast (Zarasvandi et al., 2011). 110

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[Figure 1]

Dust storms, affecting air quality and impacting social life and economy, have become increasingly frequent in Khuzestan. These storms mainly happen in the summer months and originate from neighboring countries such as Iraq, with west winds into Iran (Daniali & Karimi, 2019). Based on reports from the Khuzestan meteorological stations, just in the year 2008 total of 1035 dust storm events were reported, which is considered a significant number (Zarasvandi, 2009).

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175 2.2. Satellite Data

YYo2.2.1. Modern-Era Retrospective Analysis for Research and ApplicationsYY7Version 2 (MERRA-2)

Due to the high improvement in assimilation structure, The MERRA-2 replaced the original MERRA. It has a more advanced system including hyperspectral radiance and microwave examination. It also includes the Goddard Earth Observing System (GEOS-5) upgrade and ozone samplings of NASA, which makes it an applicable

rr) climate evaluation tool (Gelaro *et al.*, 2017). MERRA-2 benefits from the employment of a Grid-point Statistical Interpolation (GSI) climate analysis program, which is structured based on an additive analysis procedure that evaluate the incremental the meteorological data every 6 hours (Gelaro *et al.*, 2017, MERRA, 7r° 2AD).

۲۳٦ In this study, several types of MERRA-2 outputs were used, from different ۲۳۷ databases. First, the aerosol diagnosis from M2T1NXAER was used to extract surface dust mass concentration $\left(\frac{mg}{m^3}\right)$ values over Iran. The M2T1NXAER has a ۲۳۸ temporal resolution of 1 hour and a spatial resolution is $0.5^{\circ} \times 0.625^{\circ}$ longitude and ٢٣٩ latitude, respectively. M2T1NXAER records black carbon, dry dust, organic carbon, ۲٤. ۲٤١ sea salt, and sulfate aerosols in the air (Randles et al., 2017). M2I1NXLFO, also ۲٤۲ used in this paper, mainly includes land surface data. It has a Same spatial and ٢٤٣ temporal resolution to M2T1NXAER and includes parameters such as surface layer height, pressure, air temperature, wind speed, and specific humidity (Reichle et al., ۲٤٤ 2017). 720

157 2.2.2. Global Land Data Assimilation System (GLDAS)

۲٤٧ GLDAS Version 2, used in this study, is structured in three components, GLDAS-2.0, -2.1, and -2.2. The former, GLDAS-2.0 is completely in congruity with the ۲٤٨ 7 5 9 Princeton meteorological observations and covers the period 1948 to 2014. The year 2000 to present is covered by the 2.1 version. Unlike the two mentioned versions, 10. the GLDAS-2.2 observations utilized data adjustment. GLDAS-2.1 has two major 101 streams, one is associated with the Global Precipitation Climatology Project (GPCP) 101 100 precipitation products, and one is operating without it. The reason behind this is the 3 to 4-months postponement of GPCP, which forced version 2.1 to represent a 705 temporary data without it called early products. Once the GPCP product become 100

accessible the GLDAS become synchronize with it and the early products become as archive. The data used in this study are from GLDAS-2.1 and have a temporal resolution of 3 hours and a spatial resolution of 0.25°. This product is simulated with version 7 of Land Information System (LIS) from model 3.6 of NOAH. In late 2020 the 3-hourly and monthly GLDAS-2.0 products were re processed with the land mask data from MODIS-MOD44W which corrected the previous version issues such as data missing (Rodell *et al.*, 2004).

2.3. Gradient Boosting Regression (GBR) Algorithm

The boosting technique is based on aggregating a set of simple predictors. This aggregation procedure is structured by focusing on errors originated in each step till a better predictor is constructed with the least outcome error (Nie *et al.*, 2021). Considering *Y* as the target variable and $X = \{X_1, X_2, \dots, X_n\}$ as the input variables, the aim of the algorithm is to approximate G'(X) as a branch of the original function G(X) to map *X* to *Y*, so that the loss function $\mathcal{L}(Y, G(X))$ becomes minimum.

$$G'(X) = \operatorname{argmin} \mathcal{L}_{Y,X}(Y, G(X)) \tag{1}$$

By fitting the simple predictors to the \mathcal{L} at each step of the regression procedure, the Gradient Boosting (GB) algorithm tries to reduce the errors characterizing the preceding steps. This error correctional strategy increases the prediction accuracy and simultaneously decreases the bias of the prediction model. Acknowledging the m (m = 0, ..., M) as the number of Stages which GB takes to properly train a tree, algorithm first employs an initial simple predictor $G_{m=0}(X)$ and then enforces a gradient so that the \mathcal{L} is minimized. This gradient is computed as follows:

$$Y_i' = -\left[\frac{\partial \mathcal{L}(Y_i, G(X_i))}{\partial G(X_i)}\right]_{G(X) = G_{m-1}(X)}$$
(2)

^{YVY} Consider $T(X_i, \alpha)$ as a regression tree and α as the simple predictor, a new tree can ^{YVA} be structured by solving Equation (3), where α_m is the simple predictor parameter ^{YV4} at each stage and Ψ is their corresponding weight:

$$\alpha_m = \arg\min\sum_{i=1}^{N} [Y'_i - \Psi \times T(X_i, \alpha)]^2$$
(3)

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Considering β_m as each stage's optimal length, the $G_m(X)$ is updated at each iteration *m* as follows:

$$\beta_m = \operatorname{argmin} \sum_{i=1}^N \mathcal{L}(Y_i - G_{m-1}(X_i) + \beta T(X_i, \alpha_m))$$
(4)

$$G_m(X) = G_{m-1}(X) + \beta_m T(X_i, \alpha)$$
(5)

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The iteration continues until the $\beta_m T(X_i, \alpha)$ term in Equation (5) becomes its minimum possible value (Friedman, 2001). Figure shows a flowchart of the GBR algorithm.

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[Figure 2]

In this study the GB algorithm was implemented using the ensemble sub-category of the Scikit-learn library of the Python Programming language. The provided Gradient Boosting Regression (GBR) algorithm has several parameters that need to be "tuned" so that the algorithm performs as its maximum accuracy. Table 1 shows the default and optimal values for each parameter, obtained with an iterative process developed by the authors.

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Parameter	Description	Default Value	Optimal Value
loss	Enhancement approach for the loss function	Squared error	Absolute error
learning_rate	This parameter reduces the value of each tree's contribution	0.1	1.1
n_estimators	Number of boosting phases that must be accomplished	100	498
random_state	At each boosting step, this parameter sets the random seed delivered to each tree	None	34
max_depth	Individual regression estimators' maximum depth	3	1
min_samples_leaf	Number of minimum samples needed to consider a node a leaf node.	1	45

Table 1: Gradient Boosting Regression (GBR) parameters.

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Y9Y 3. Results

3.1. Selection of Year and Region of Focus

MERRA-2-M2TMNXAER monthly SDMC data for Iran were downloaded from the 299 NASA website for 2009 2020 ۳.. the period between and ۳.۱ (https://disc.gsfc.nasa.gov/datasets/M2TMNXAER_5.12.4/summary?keywords=M2TMNXAER). This satellite provides monthly averaged aerosol diagnosis with spatial resolution of ۳.۲ $0.5^{\circ} \times 0.625^{\circ}$. Considering this resolution there were total of 1056 observational ۳.۳ grid cross-section points over the Iran. By calculating the maximum value of SDMC 3.5 among the 12 months in each specific year and at each of 1056 points, Figure 3 ۳.0 shows the distribution of yearly maximum SDMC (mg/m^3) over Iran for the period ۳.٦

 $r \cdot v$ considered. For better understanding of each specific year ranking based on SDMC $r \cdot A$ level, thier Annual Maximum (A.M.) has been noted in the figure.

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[Figure 3]

Figure 3 shows that the southern and southeastern sections of Iran, including the 31. provinces of Khuzestan and Hormozgan as well as Sistan and Baluchestan, are 311 highly prone to large dust concentrations. The Khuzestan province appears to be the 311 most impacted province and is the focus of this investigation. Over the 12-year 313 315 period considered, Iran was overall characterized by minimum, mean and maximum SDMC values of 0.04, 0.295 and 1.36 mg/m^3 respectively. The year 2018, as the 310 vear with highest SDMC observed value (~1.36 mq/m^3) was selected as the study 317 period in current study. 311

3.2. Input Variable Correlation Analysis

Having selected the year and region of focus, SDMC data for the year 2018 for the
Khuzestan province was extracted based on outputs extracted from MERRA-2M2T1NXADG

(https://disc.gsfc.nasa.gov/datasets/M2T1NXADG_5.12.4/summary?keywords=M2T1NXADG),

consisting of 1-hour time averaged aerosol diagnosis data with the same spatial
resolution as MERRA-2-M2TMNXAER. 1-hour data was converted to daily data
by taking the maximum value within each 24-hour period, therefore obtaining 365
SDMC values.

As mentioned, the Khuzestan province is characterized by different types of climate conditions due to its significant variation in land elevation; therefore 18 Research Points (RPs) were considered in this study, equally distributed across the province (with latitudinal and longitudinal spacing of 0.5° and 0.625°, respectively, same as

the resolution of MERRA2-M2T1NXADG). These include the cold region in the north as well as the extremely hot regions in the south.

Then, several hydrological, meteorological and geological outputs from Global Precipitation Measurement (GPM), Global Land Data Assimilation System (GLDAS), MERRA-2-M2I1NXLFO and MERRA-2-M2T3NVASM with various spatial and temporal distribution were extracted. Table 2 lists these variables, which are the 11 input variables considered for SDMC prediction in this study, with their units and corresponding satellite.

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Table 2: Input variables considered for SDMC prediction.

Satellite	Variable	Description	Units
	Acond	Aerodynamic conductance	m/s
	Esoil	Evaporation flux from soil	kg/m²s
GLDAS	Qh	Surface upward sensible heat flux	W/m^3
	Evap	Evapotranspiration	kg/m²s
	SoilMoist	Surface soil moisture	kg/m^2
	PS	Surface pressure	Ра
MERRA-	TLML	Surface air temperature	K
2	SPEEDLML	Surface wind speed	m/s
-	QLML	Surface specific humidity	_
	HLML	Surface layer height	m
GPM	Precip	Precipitation rate	mm

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The Pearson's Correlation Coefficient (PCC) was computed to quantify the correlation of each of the 11 variables in Table 2 with daily SDMC. While there are other alternatives, such as Spearman's or Kendall's rank correlation, various studies found the efficiency and robustness of PCC, especially in handling data with non-

apparent outliers and non-linearity (Chok, 2010, Hauke & Kossowski, 2011,
Rebekić *et al.*, 2015).

Figure 4 contains the relative PCC heat map for the 18 RPs, including the average ٣٤٧ PCC values over all the RPs. The three parameters with the highest PCC value, ٣٤٨ surface wind speed SPEEDLML (PCC = 0.61), aerodynamic conductance ACOND 329 (PCC = 0.57) and surface pressure PS (PCC = 0.53), were selected as input ۳0. variables for real-time daily SDMC prediction with the GBR algorithm. PS denotes 301 307 the atmospheric surface pressure that directly controls the movement of air masses from regions with low pressure to regions with higher pressure (Gomis et al., 2008, 303 Guo et al., 2011). The surface aerodynamic conductance (ACOND) describes the 302 000 effect of surface roughness on the movement of air masses (S. Liu et al., 2007, 301 Mallick *et al.*, 2018).

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[Figure 4]

From Figure 4, the hydrological parameters rainfall, relative humidity and evapotranspiration have the least correlation with SDMC in the Khuzestan province.

71. 3.3. Real-Time Prediction of SDMC

The three input variables for prediction, known at the current time (day) "t", were used in the GBR algorithm to predict the current time SDMC. This was done for all 18 RPs and the prediction performance was evaluated using four indices, PCC, Nash-Sutcliffe Efficiency (NSE), Normalized-Root Mean Squared Error (N-RMSE) and Normalized Mean Absolute Error (N-MAE). Results of these metrics which have been widely used in earth and water research fields (Jodar-Abellan *et al.*, 2019, Moriasi *et al.*, 2007, Pardo *et al.*, 2020), are shown in Table 3.

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RPs	PCC	NSE	N-RMSE	N-MAE
P1	0.716	0.493	0.710	0.494
P2	0.771	0.585	0.642	0.453
P3	0.815	0.632	0.605	0.422
P4	0.648	0.397	0.774	0.446
P5	0.707	0.473	0.723	0.516
P6	0.793	0.621	0.613	0.437
P7	0.783	0.598	0.632	0.455
P8	0.706	0.457	0.735	0.518
P9	0.720	0.490	0.712	0.507
P10	0.686	0.451	0.738	0.517
P11	0.505	0.170	0.908	0.613
P12	0.701	0.481	0.718	0.494
P13	0.684	0.425	0.756	0.563
P14	0.525	0.223	0.878	0.628
P15	0.405	0.079	0.957	0.594
P16	0.541	0.253	0.862	0.618
P17	0.435	0.139	0.925	0.702

0.095

0.948

0.649

Table 3: SDMC real-time prediction performance for the 18 Research Points

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considered.

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P18

0.398

Values in Table 3 vary across the RPs but, overall, the average PCC, NSE, N-RMSE 3773 and N-MAE are within an acceptable range. The P3 Research Point (CC = 0.815, ۳۷۳ NSE = 0.632, N - RMSE = 0.605 and N - MAE = 0.422) is characterized by ۳۷٤ the best prediction performance. Figure 5 highlights a clear pattern of better 370 prediction performance in the southern regions of the province. This figure has been 371 obtained using the Inverse Distance Weighting (IDW) interpolation method over the 377 Khuzestan province based on the calculated performance indices of 18 research ۳۷۸ points. ۳۷۹

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[Figure 5]

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3.4. Future Forecasting of SDMC

For the P3 Research Point (best real-time SDMC prediction, see previous section),
future forecasting of SDMC was considered for lead times of 't-2', 't-4', 't-6' and
't-8' (input data from 2, 4, 6 and 8 days prior to the current time 't' for which SDMC
is forecasted). PCC values were calculated to quantify the correlation between the
current time SDMC (at time "t") and the 11 input variables from Table 2 for the four
lead times. Figure 6 shows the PCC values in a circular bar chart.

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[Figure 6]

From Figure 6 it can be seen that, analogously to the case of real-time prediction, precipitation and surface specific humidity have the lowest correlation with the SDMC. PS and surface upward sensible heat flux Qh and surface air temperature TLML correlations with SDMC show a significant increase when moving backward in time.

Based on the PCC analysis and using a procedure based on progressive elimination of input variables with lower and lower PCC value, a procedure applied in other previous studies (Sharafati, Asadollah, & Hosseinzadeh, 2020, Sharafati, Asadollah, & Neshat, 2020), combinations of the 11 input variables from Table 2 were constructed for future forecasting of SDMC (lead times of 't-2', 't-4', 't-6' and 't-8') using the GBR algorithm. The combinations considered are listed in Table 4.

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Combination	Input Variables
C1	PS (t-4), PS (t-6), PS (t-2), PS (t-8), Qh (t-2), Qh (t-4)
C2	PS (t-4), PS (t-6), PS (t-2), PS (t-8), Qh (t-2)
C3	PS (t-4), PS (t-6), PS (t-2), PS (t-8)
C4	PS (t-4), PS (t-6), PS (t-2)
C5	<i>PS</i> (<i>t</i> -4), <i>PS</i> (<i>t</i> -6)
C6	PS(t-4)
C7	PS(t-2), Qh(t-2)
C8	PS (t-4), Qh (t-4)
С9	PS (t-6), TLML (t-6)
C10	PS (t-8), TLML (t-8)

Table 4: Input variable combinations for future forecasting of SDMC.

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Figure 7 summarizes the prediction performance of the GBR algorithm for future
forecasting of SDMC using the ten input variable combinations in Table 4, evaluated
based on the PCC, NSE, N-RMSE and N-MAE indices.

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[Figure 7]

٤١٣ From Figure 7, the prediction performance decreases when moving from lead time 't-2' to 't-8' for the input variables, as also observed in previous studies (Sharafati, ٤١٤ Haji Seyed Asadollah, et al., 2020). The C1 input variable combination, including 210 the highest number of input variables (six), is associated with the best prediction 517 performance (PCC = 0.698, NRMSE = 0.733). However, the C6 input variable ٤١٧ combination, including only one variable (PS (t-4)) shows only an 8% reduction in ٤١٨ accuracy (PCC = 0.640, NRMSE = 0.781), which is considered an insignificant ٤19 performance reduction. C6 is therefore the optimal input variable combination, ٤٢٠ because it only requires the knowledge of a single variable (PS). The preferable use ٤٢١ of lead time 't-4' is also confirmed by the high performance of the C8 input variable ٤٢٢ combination (PCC = 0.665, NRMSE = 0.759). ٤٢٣

٤٢٥ **4. Discussion and Conclusion**

Being able to forecast Particulate Matter (PM) concentrations is essential, due to its effects on human life, economy and environment. This study aimed to simulate Surface Mass Dust Concentration using the Modern-Era Retrospective analysis for Research and Applications Version 2 (MERRA-2) aerosol satellite diagnosis. To do this, monthly SDMC data for the period 2009 to 2020 were downloaded from the MERRA-2 database.

٤٣٢ The monthly evaluation of air dust distribution in Iran showed that the southeastern ٤٣٣ regions are characterized by higher dust concentrations, negatively affecting air quality. The province of Khuzestan is the most impacted, as also confirmed by other ٤٣٤ investigations (Sabetghadam et al., 2018, Yousefi et al., 2020), and was therefore 280 selected as the case study. The year 2018 was specifically considered, because it was 277 characterized by high SDMC and has complete recorded satellite observations. ٤٣٧ ٤٣٨ SDMC hourly data were obtained from MERRA-2 for 2018 for the Khuzestan province. ٤٣٩

Pearson's Correlation Coefficient (PCC) computation to evaluate the correlation ٤٤. between MERRA-2 SDMC and 11 meteorological, hydrological and geological ٤٤١ parameters from Global Precipitation Measurement (GPM), Global Land Data ٤٤٢ Assimilation System (GLDAS) and another MERRA-2 database showed the wind-٤٤٣ 222 related variables - surface wind speed (SPEEDLML), surface aerodynamic conductivity (ACOND) and surface pressure (PS) - to be the most correlated with 220 SDMC. Combinations of these three parameters were evaluated for real-time 557 prediction of SDMC using the Gradient Boosting Regression (GBR) algorithm at 18 ٤٤٧ Research Points. The best prediction performance was obtained at Research Point 3 ٤٤٨ (CC = 0.815 and N - RMSE = 0.605), which was considered for the further 559 forecasting analysis. The input variables are solely based on remote sensing (one of ٤0.

the elements of novelty of this study), therefore the related errors and uncertainties 201 are expected to affect the SDMC prediction performance, compared to models using 205 ground-based measurements. However, while for some Research Points the GBR 208 algorithm produced predictions with PCC value in the moderate acceptance range 202 $(0.3 \le PCC \le 0.7)$ based on (Ratner, 2009), there are several Research Points where 200 the prediction performance was strong $(0.7 \le PCC \le 1.0)$. This outcome confirms 207 the prediction potential of ensemble algorithms when using data affected by errors 507 and modelling processes characterized by non-linearity. Comparing this study's 501 results with those by (Nabavi et al., 2018) shows that the GBR algorithm 209 outperforms both SVM (PCC = 0.81) and MARS (PCC = 0.80). The GBR also ٤٦. appears to have better accuracy than ANN (PCC = 0.62), ANFIS (PCC = 0.70) and 521 GRNN (PCC = 0.71) (Mirzaei *et al.*, 2019). From a spatial point of view, our results ٤٦٢ highlighted a better prediction performance for the southern low lands of the ٤٦٣ Khuzestan province, when compared with the higher and mountainous lands in the ٤٦٤ 270 north. Predictions were also better in marshlands compared with rocky soils.

577 While the wind-related input variables govern the real time ('t') prediction of SDMC, the heat-related variables are also important for the future forecasting of ٤٦٧ SDMC (lead times of 't-2' to 't-8'). Considering Research Point 3 for the analysis, ٤٦٨ the PS variable allows for the better forecasting, closely followed by surface upward 279 ٤٧٠ sensible heat flux (Qh) and surface air temperature (TLML). It is worth mentioning that, as the lead time goes from 't-2' to 't-8', the influence of TLML on SDMC ٤٧١ forecasting becomes stronger than that of Qh. The evaluation of input variable ٤٧٢ combinations for future SDMC forecasting revealed that the use of a single input ٤٧٣ variable, PS (t-4), with PCC = 0.640 and N - RMSE = 0.781, is the optimal ٤٧٤ approach (most cost-efficient and applicable). To the authors' knowledge, there are ٤٧٥ no previous studies specifically aimed at forecasting future air pollutant 577

concentrations. The future forecasting performance obtained here with the GBR
 algorithm is comparable with previously presented real-time predictions.

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EA. Declaration of interests

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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٤٨٦ **References**

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Figure 1: Location of the Khuzestan province in Iran with (a) Research Point distribution and (b) Digital Elevation Model (DEM).



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A.oFigure 3: Yearly maximum Surface Dust Mass Concentration (SDMC) between 2009 and 2020A.oin Iran.



Research points

Figure 4: Heat map of Pearson's Correlation Coefficient (PCC) between the 11 input variables**6.9**considered and daily SDMC for the 18 Research Points.

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Figure 6: Pearson's Correlation Coefficient for correlation between the 11 input variables considered and SDMC for different lead times.

