1	Optimal load scheduling for off-grid
2	photovoltaic installations with fixed
3	energy requirements and intrinsic
4	constraints
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22	ABSTRACT
23	Solar energy is one of the most promising green energy sources. On-grid photovoltaic installations supply
24	energy to consumers as a support energy source, but in isolated areas, it comes as the unique source. The
25	decision-maker must dimension the installation, maintaining system performance with reasonable
26	investments. In some scenarios, the utility manager can handle the energy delivered to consumers as every
27	subsystem can be independently connected. A strategy for scheduling the energy consumption to decrease
28	the number of photovoltaic modules required in a standalone system is proposed here. The problem
29	formulation corresponds to generalising a more specific problem before published. We presented a real case
30	study being the groups of hydrants that provide water to crops in a pressurized irrigation system for energy
31	consumption to schedule.

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32 33

- 33 Keywords: energy efficiency; photovoltaic energy; solar plant size optimization
- **1. INTRODUCTION**

35 Photovoltaic (PV) systems have increased in the last times, covering fields with 36 limited applications. But, in productive activities, the PV panels installation is large capital 37 expenditures that can reduce the incomes and increase the payback period making it 38 unaffordable. Then, procedures for the optimal design of photovoltaic plants are 39 necessary. Typical approaches to the design problem are based on the guarantee of 40 energy under the worst case. Special development of research has emerged around 41 hybrid installations as PV-diesel (Xue, 2017) or PV-ES (energy storage) plants (Dufo-López 42 and Bernal-Agustín, 2005; Kaldellis et al., 2010; Perez, E.; Beltran, H.; Aparicio, N.; 43 Rodriguez, 2013). Design of big plants are defined by their problems and has also been an 44 object of study in (Beltran et al., 2012).

Solar energy production becomes one of the hottest topics in the water industry as irrigation occurs in isolated areas (no grid connection) and pressurized irrigation networks (PINs) are very energy hungry. For the last 70 years, irrigation networks shifted from gravity-fed irrigation into pressurized irrigation (PIN). The irrigated area grew 2.5 times, water consumption doubled and energy expenditure multiplied by 19 in Spain (Corominas, 2010). These enormous figures show efficient management of PIN has become of paramount importance (Moradi-Jalal and Karney, 2008; Pardo et al., 2018).

52 Given that the anthropic pressure influences the environment, the photovoltaic 53 (PV) technology incorporates in the agriculture industry, like green (no emissions) and

profitable choice to conventional power sources (Mérida García et al., 2019). Solar power management comes from one of the trendiest questions in the water industry (Aliyu et al., 2018; Chandel et al., 2015). Energy production in PV systems expanded overall energy production from 29.5 (2012) to 107 (2018) GW (Jäger-Waldau, 2019). This momentum is because of a shift to better large-scale service systems, shifts in legislation, and a universal devaluation of PV modules prices (Goodrich et al., 2013) (30–60% in 10 years; (Closas and Rap, 2017)).

61 Many researchers analysed how to convert direct-drive pumping devices fed by 62 electricity grids into a standalone (off-grid) direct solar waterpower system (SPWS) (Betka 63 and Attali, 2010; Elkholy and Fathy, 2016; Mohanty et al., 2018; Pardo et al., 2020a; Ru et 64 al., 2013). Converting water pressurized network (WPN) into a standalone full PV supplied 65 system involves accumulating energy in head tanks or batteries. But, in irrigation, the 66 utility manager may regulate water (not in urban WPNs) and energy expenditure (Pardo 67 et al., 2018). Standalone systems are the most widespread solution around the world 68 because of simplicity, great efficiencies and adaptable to all sizes and irrigation methods 69 (Hartung and Pluschke, 2018). Other optimisation problems have significant interest and 70 an inherent difficulty, as determining the best tilt angle on locations under high diffusive 71 and reflective factors (Gökmen et al., 2016; Kerekes et al., 2012). Design problems in 72 extreme conditions involve considering other restrictions as cooling needs (Karira et al., 73 2004).

Scheduling problems to minimise (or maximise) an objective function by satisfying
 some set of constraints is frequently studied. To name a few, there are scheduling jobs in

76 machines (Liu and Yang, 2011; Luo and Chu, 2006; Pham et al., 2007), transportation 77 (Forouharfard and Zandieh, 2010; Shrivastava et al., 2002; Thengvall et al., 2003), 78 computer task scheduling (Chrétienne, 1989; Feitelson et al., 1996; Moore, 2004, 2003) 79 and energy optimising (Ahmed et al., 2017). These optimisation problems are hard to 80 solve because of the size of the configuration space. By example, the job shop problem 81 (JSP) (Fang et al., 1996; Gholami and Zandieh, 2009; Hefetz and Adiri, 1982; Koonce and 82 Tsai, 2000; Nakano and Yamada, 1991) is known as an example of NP-complete problems 83 (nondeterministic polynomial time).

84 The proposed algorithms to solve scheduling problems are non-deterministic 85 (Forouharfard and Zandieh, 2010; Liu and Yang, 2011; Luo and Chu, 2006; Pham et al., 86 2007; Shrivastava et al., 2002; Thengvall et al., 2003), (Fang et al., 1996; Gholami and 87 Zandieh, 2009; Hefetz and Adiri, 1982; Koonce and Tsai, 2000; Nakano and Yamada, 88 1991). For instance, genetic algorithms (Fang et al., 1996; Gholami and Zandieh, 2009; 89 Nakano and Yamada, 1991; Shrivastava et al., 2002) are suitable for optimisation 90 problems where the space of configuration is too big to be explored using a deterministic 91 algorithm in workable computing time, or where the objective function presents local 92 extremes. But the algorithm does not guarantee to get the global best solution to the 93 problem (a limiting characteristic).

The present paper considers a case of the scheduling problem. It corresponds to the design of a photovoltaic (PV) installation where PV panels supply electricity to feed a pumping device in a pressurised irrigation network. In this approach, the irrigation

97 network runs as a standalone SPWS and we intend to quantify the effect of selected
98 schedule in a rigid rotation predetermined scheduled PIN (Replogle and Kruse, 2007).

99 The irrigation network complies a set of devices (hydrants, units and subunits) 100 constrained to have a fixed time of operation. Two more requirements apply. The first is 101 fixed operation time (water delivered to crops in every consumption node must be 102 similar) but we can divide this period into intervals. The second is that the power 103 consumption of the set of devices can depend on the connected appliances (nodes with 104 high elevation far from the pumping system need more energy supplied by the pumping 105 system).

106 For a set of devices with given shared consumption profiles, we parametrised the 107 problem with the working times (hydrants opened supplying water to crops) and the 108 number of intervals in which the day is divided. We have presented a restricted version 109 of this problem (Pardo et al., 2018) applied to water pumping systems. We determine the 110 optimal job scheduling to decrease the number of required solar panels for the power 111 supply installation by the number of simultaneous devices (Q) and the number of time-112 slices (N). In (Pardo et al., 2018), we solve the problem by exploring the space of allowed combinations, composed by $Q \cdot 2^N$ configurations. But this method is not useful for big 113 114 cases because of its dependence on the parameters Q and N. We develop a genetic 115 algorithm to find the schedule minimise differences between the aim and the real injected 116 flows (Pardo et al., 2020b). This earlier approach shows that it is impossible to calculate the $Q \cdot 2^N$ combinations. The present paper exploits a property of the feasible solutions 117 118 that reduce the subset of the configuration space that is admissible as a solution. The fast-

119	numerical	algorithm	developed	in	this	investigation	guarantees	the	solution	with	а
120	computati	onal compl	exity of $O(\zeta$	<i>)</i>).							

121	The rest of the paper is organised as follows. Section 2.1 exposes the problem and
122	section 2.2 presents the basis of solar irradiance and clear sky models. Section 2.3 shows
123	the objective function to minimise and 2.4 presents the formulation of the problem;
124	Section 3 shows the case study where to solve the problem and Section 4 presents the
125	solution for the optimal size design problem. and the discussion about the research.
126	Finally, Section 5 highlights the conclusion.

- 127
- 128 129

2. MATERIALS AND METHODS

- 130 **2.1. Prok**
- 131

2.1. Problem exposition

132 Let us consider the problem of designing a PV plant for supply *d* devices in several 133 states (connected or powered off would be the simplest case), numbered from zero 134 (powered off) to S:

135
$$s \in \{0,1,..S\}$$
 (1)

Let call each one of the allowed combinations a system configuration, represented
by the d-dimensional vector ζ:

138
$$\zeta = \{(s_1, \dots, s_d) | s_i \in \{0, 1, \dots S\}\} \subset N^d.$$
 (2)

139 Where S^d combinations may appear. Each with a power consumption function given by 140 $c(\zeta)$.

141 Let us consider a work schedule for the devices of a determined system 142 corresponding to a day. With different needs on different days, we would realise the

- 143 overall process for each day. If we divide the day into N slices, $\{t_1, t_2, ..., t_N\}$, with size
- 144 $\Delta = 24/N$, there will be S^{d·N} possible daily combinations for the system. We show a working



145 plan example in Table 1.



146 A working plan is then, a set of states associated with the group of slices, 147 $\Pi = \{\zeta(t_k)\}_{k=1}^N$. Given a working plan, it is possible to calculate the total power 148 consumption and time of operation:

149
$$P = \sum_{k} c(\zeta(t_k)).$$
(3)

150
$$T = \Delta \cdot \sum_{i,k} Ind\left(\xi^{i}(t_{k})\right), \tag{4}$$

151 where Ind(x) is the indicator function defined as:

152
$$Ind(x) = \begin{cases} 1 & x \neq 0 \\ 0 & x = 0 \end{cases}$$
 (5)

153 Also, representing by $E(t_k)$ the maximum power for generation by one PV panel 154 at a time t_k , the number of panels needed at this time is:

155
$$n(t_k) = \frac{c(\zeta(t_k))}{E(t_k)}.$$
 (6)

156 And the number of panels needed by a working plan is:

157
$$\eta = \max_{k \in [1, N]} (n(t_k)).$$
(7)

158 A power-time representation of a working plan is a plot of the function $c(\zeta(t))$ as

159 Figure 1:



Figure 1. Power-time representation of a working plan

- 160 **2.2. Model of maximum hourly solar irradiance**
- 161
- 162 **2.2.1.** Basis of hourly solar irradiance
- 163

164 Let us introduce briefly some concepts and terminology that will be needed in the

rest of the paper (for a more in-depth discussion see (Badescu, 2014; Cao and Lin, 2008;

- 166 Page, 2012; Wald, 2018)).
- 167 The irradiance E is the power received per area (Watt per square meter). To
- 168 calculate solar irradiance at ground level the first step is to consider its value on a normal

horizontal surface at the top of the atmosphere (E_{0N}), and the value corresponding to a

170 horizontal surface situated in the same point E_0 , given by:

171
$$E_0 = E_{0N} \cdot \cos(\theta_s), \tag{8}$$

172 where θ_s is the solar zenithal angle, related to the latitude of the point (Φ) and the 173 declination of the sun (δ) through the equation:

174
$$\cos(\theta_s) = \sin(\Phi) \cdot \sin(\delta) + \cos(\Phi) \cdot \cos(\delta) \cdot \cos(\omega),$$
 (9)

where ω is the hour angle measured from the local meridian to the position of the sun at each instant. Introducing the reduced time coordinate t, with t=0 at solar noon, the hour angle can be written as:

178
$$\omega = \frac{\pi}{12} \cdot t. \tag{10}$$

179 Let consider a panel facing south with an inclination given by the angle β (tilt) 180 concerning the horizontal. The angle of incidence of the solar rays can be obtained as a 181 modification of the expression (9):

182
$$\cos(\hat{t}) = \sin(\Phi - \beta) \cdot \sin(\delta) + \cos(\Phi - \beta) \cdot \cos(\delta) \cdot \cos(\omega). \tag{11}$$

183 From equation (11) the energy of the incident direction will have an expression:

184
$$E_{lin}(t) = A + B \cdot cos(\omega(t)).$$
(12)

The atmosphere affects the values calculated before because of light scattering causes the dispersion of light around the incident direction (depending on the wavelength). Then, the effective energy received at ground depends on the amount of atmosphere that must be crossed.

189 Also, the radiation that is reflected on the ground can impact in the solar panel190 contributing to the generated power. At ground level, the total irradiance is the sum of

191	radiation that comes directly from the direction of the sun (direct or beam radiation),
192	radiation originated by scattering processes in the atmosphere (diffuse radiation) and the
193	radiation coming from the ground (albedo), a fraction of the total radiation that falls upon
194	it (reflected radiation).
195	But even if we perform the calculations using all the precision, some factors scape
196	from the equations and must be determined in situ (for instance, influence from the local
197	topography in the values of the albedo). Moreover, the randomness of nature appears in
198	the form of clouds or other meteorological elements that break the validity of the
199	forecast.
200	We calculate here the least number of PV panels required to feed the energy
201	demand using a curve of hourly power generation representative of the set of panels used
202	in the installation calculated with the Duffie and Beckman equations (Duffie and
203	Beckman, 2013).
204	2.2.2. Clear sky models
205 206	Equation (12) only considers the effect of direct radiation, but as we introduced

206 Equation (12) only considers the effect of direct radiation, but as we introduced 207 previously, several other contributions determine the total power. The light beam is 208 dispersed following a three-dimensional angular distribution around the direction given 209 by the direct beam, and part of the energy arrives at the panel in angles different from 210 that given by (12). Inclusion and calculation of diffuse irradiance is not a simple problem 211 (see (Behar et al., 2015) for a comparison of the models).

The problem of determining the maximum irradiance available at any determined instant is studied using a class of models called clear sky models. Clear sky models

complement equation (12) considering the contribution of incident beams with directiondifferent from the direct one.

216 There exist a great variety of clear sky models, as can be seen in [59, 60]. Each 217 model considers different dispersion terms, but a common characteristic of these terms 218 is that they depend on the amount of atmosphere traversed by the light. A measure of 219 this distance is the parameter called air mass, which depends on the zenithal (or 220 equivalently the solar elevation) angle, related through equation (9) with the hour angle. 221 For elevation angles greater than 20-30 degrees, the value of air mass can be considered 222 constant. It is for smaller angles that the different models predict different values. 223 However, the final behaviour is similar in the most of models, that is a reduction 224 concerning considering only the direct beam given by (12) of irradiance at solar noon and 225 an increment of the generated power for earliest and latest moments of the day. As a 226 result, the power generated by the panel changes respect to the direct component as it 227 is shown in Figure 2.



Figure 2. Models for the power generation of the PV panel. The dotted line corresponds to the direct beam, while the continuous curve represents the result when the diffusion component is included. The difference is exaggerated to show the effect.

An example is the Kasten–Czeplak model, given by the equation:

228 Kasten–Czeplak: $G_c = A \cdot cos\theta_z + B$. (13) 229 where G_c is clear sky global radiation. 230

2.3 Objective function
232 Let us consider now the solution to the problem introduced in Section 2.1. Given
233 the equations (6) and (7), the difference between them can be considered a measure of
234 the under- or oversizing of the plant for a required power load, so an objective function
235 can be defined as:

236
$$f(n_1, \dots, n_N) = \sum_{k=1}^N (\eta - n_k)^2,$$
 (14)

237 where $(n_1, ..., n_N)$ are the number of panels used in each interval and η is 238 optimum.

239 Then, the optimal condition over is given by the null partial derivatives:

240
$$\partial_i f = 2 \cdot \sum_{k=1}^N (\eta - n_k) \cdot \delta_{ki} = 0, \tag{15}$$

for every index i, so the solution is:

242
$$n_1 = n_2 = ... = \eta.$$
 (16)

That is, the optimum is got when the number of required panels is the same at every time, so the problem is to schedule a balanced load on the system, modifying the working plan to obtain a constant ratio between the load and the available power at each instant under the time operation constraint T.

247

249

248 **2.4. Optimization Algorithm**

At any time, the number of active devices varies from 0 to Q (if there is no constraint over the simultaneity in device working, this number would be the number of devices d). Depending on the vector ζ the consumption can vary, so let introduce

253
$$\pi_{(q)} = \min c(\zeta), \text{ where } \sum_{i} Ind\left(\xi^{i}(t)\right) = q.$$
(17)

Additionally, the problem is characterized by two different regimes of power demand. At the first and last hours, the demand determines the need for power, but in the central hours, the power generated exceeds the system needs. So, the optimization problem is determining the connection $t_{(+q)}$ and disconnection time $t_{(-q)}$ with q from 1 to the maximum allowed number of simultaneous devices Q (Figure 3).



Figure 3. Example of power demand for Q=3 and curve of maximum power

supply.

259 From equations (6) and (16):

260
$$\frac{\pi_{(1)}}{E(t_{(\pm 1)})} = \frac{\pi_{(2)}}{E(t_{(\pm 2)})} = \dots = \frac{\pi_{(Q)}}{E(t_{(\pm Q)})} = \eta.$$
(18)

261 This implies that:

262
$$t_{(\pm q)} = E^{-1} \left(\frac{\pi_{(q)}}{\pi_{(Q)}} \cdot E(t_{(\pm Q)}) \right).$$
(19)

As the total time of working for each device is fixed, any modification of its connection time is got diminishing the number of connected devices from q to q-1 at this moment. Considering the symmetry of the power curve, $t_{(+q)} = -t_{(-q)}$, and expression (4) takes the form:

267
$$T = \sum_{q} \left(t_{(-q)} - t_{(+q)} \right) = 2 \cdot \sum_{q} t_{(-q)} .$$
 (20)

268 Now, the problem is equivalent to obtaining the solution of the following 269 equation, valid from noon to sunset.

270
$$E^{-1}\left(\frac{\pi_{(1)}}{\pi_{(Q)}} \cdot E(t_{(-Q)})\right) + \dots + E^{-1}\left(\frac{\pi_{(Q-1)}}{\pi_{(Q)}} \cdot E(t_{(-Q)})\right) + t_{(-Q)} = \frac{T}{2}$$
(21)

271 For the clear sky model derived from equation (13), the solution can be obtained

through an analytic expression given by:

273
$$\operatorname{arccos}\left(\frac{\frac{\pi_{(1)}}{\pi_{(Q)}} \cdot E(t_{(-Q)}) - B}{A}\right) + \dots + \operatorname{arccos}\left(\frac{\frac{\pi_{(Q-1)}}{\pi_{(Q)}} \cdot E(t_{(-Q)}) - B}{A}\right) + t_{(-Q)} = \frac{T}{2} .$$
 (22)

274 We calculate the parameters A and B from equation (13).

In the general case, the equation (21) can be solved using by example a Newton-Raphson approach. This solution can be applied to solve the problem of scheduling the pump connection time presented in [26] in a numerical, faster and exact form.

279

280 2.5. Pseudocode

281The algorithm to calculate the optimum size for the PV installation is based on the282developments and equations presented before. In a short exposition:

283 Equation (16) states for the main result of the algorithm. The relation between the

- available and required power must be constant in all the critical times, corresponding
- with the connection and disconnection moments as Figure 3 illustrates.
- 286 Equation (4) represents the constraint corresponding with the total working time

of the installation.

288	Equation (6) introduces the expression for calculating the number of required
289	panels at any time. Using it in equation (16) derives in equations (18) and (19).
290	Finally, equation (21) is obtained from the equations (4) and (19) and represents
291	the expression that resumes the optimization problem as a non-linear equation that can
292	be solved for different irradiance models, as it is done, by example, in equation (22).
293	The pseudocode corresponding to the algorithm is the following:
	Algorithm 1 Optimize installation scheduling and size

Input: Q: Number of maximum simultaneous devices, $\pi_q(i)$: Power consumption of each allowed configuration i of q devices, T: Total work time of the installation Output: $t_{(-1)}, .., t_{(-Q)}$: Disconnection times, N_{opt} : Number of pannels procedure OptimizeInstallation for q from 1 to Q do $\pi_{(q)} \leftarrow min(\pi_q(i))$ Minimum power of q devices /*Solve nonlinear equation*/ $t_{(-Q)} \leftarrow Root(\sum_{k=1}^{Q-1} E^{-1}(\pi_{(k)}/\pi_{(Q)} * E(x)) + x - T/2 = 0)$ $N_{opt} \leftarrow E(t_{(-Q)})/\pi_{(Q)}$ ▷ Calculate Nopt for i from 1 to Q - 1 do $\begin{array}{c} t_{(-i)} \leftarrow E^{-1}(\pi_i/N_{opt}) \\ \text{return } t_{(-1)}, .., t_{(-Q)}, N_{opt} \end{array}$ \triangleright Calculate disconnection time t_i

Figure 4. Flowchart Optimization process.

295

294

3. CASE STUDY

297

298 Figure 5 shows the Albamix network layout, located in Comunidad Valenciana.

299 This PIN comprises 132 nodes and 4.05 km of PVC pipes. It supplies water to 167.7 ha to

300 irrigate orchards containing different varieties of citrus fruit. The minimum service

301 pressure required is $\left(\frac{p}{\gamma}\right)_{threshold}$ = 25 meters of the water column. We grouped the 302 irrigation networks into five segments. The water demands for each segment were 303 around 80-85 L/s. The irrigation management system is a central system scheduled 304 delivery and the total irrigation time presents monthly variation. We recover 305 meteorological information to calculate water demands. We compute the reference crop 306 evapotranspiration using the Penman-Monteith method. The irrigation time values are 307 shown in Table 2.



308

Figure 5. General Layout of the PIN.

Month	January	February	March	April	May	June
Irr. time (h)	0.52	0.69	1.12	1.29	1.93	2.92
Month	July	August	September	October	November	December
Irr. time (h)	3.25	2.70	1.62	0.75	0.43	0.30

Table2. Monthly irrigation time in Albamix network.

309	In July (the month with the highest water requirements), every segment should
310	be irrigated for 3.25 h/day (Table 2). The network features are incorporated into a
311	hydraulic simulation software such as EPAnet (Rossman, 2000) which represents reality.
312	The energy consumption in pumps and nodes (Pardo et al., 2013) are calculated using
313	UAEnergy (M.A. Pardo et al., 2019).
314	
315 316	3.1. Practical restrictions The utility manager operates a PIN dimensioned for delivering water during nights
317	to exploit low electricity tariffs. Solar irradiance produces energy, but the irrigation time
318	decreases. In local conditions, the number of hours in which it produces photovoltaic
319	energy can be 9h and according to the values showed in Table 2 and the number of
320	segments, the irrigation time is 3.25*5 = 16.25h.
321	.Given that irrigation time is lower, higher flow rates and higher headlosses owing
322	to friction in the pipes are likely. We defined the upper and lower network flowrate
323	threshold ($Q_{up,th}$ =194.9 l/s, $Q_{low,th}$ =152.5 l/s) as the highest flowrate injected
324	maintaining the pressure above the standards and the least injected flow not meeting
325	pressure requirements (M A Pardo et al., 2019). The flowrate availability is another
326	constraint. It is the maximum flow rate that can be delivered. If the injected flow is lower
327	than the flowrate availability, no limitation arises in our optimisation problem.
328	The working time is 9 hours in the month with higher irradiance (July) in these
329	latitudes as a consequence of the technical characteristics of the inverter.

330

331 3.2. Seasonal variation

332

333 Many considerations regulate power management in PV modules (tilt angle, 334 latitude, azimuth, temperature, etc.). Seasonal variation is a well-known fact, the smallest 335 solar irradiation level occurs in winter while the highest in summer (Bou-Rabee and 336 Sulaiman, 2015; Osinowo et al., 2015; Pardo et al., 2020a) in these latitudes. On the other hand, water and energy demands are higher during summer and this 337 338 period coincides with greater energy production. The utility manager must conduct a 339 hydraulic test (considering the network details) to choose the most adverse month. The 340 PV modules must be sized for the worst month (the month selected to size the system). 341 In this month, the pump can operate enough hours to guarantee crops irrigation. 342 343 4. **RESULTS AND DISCUSSION** 344 345 4.1. Energy production variation 346 347 We figured out the monthly energy production and consumption to establish July 348 as the most unfavourable month (M A Pardo et al., 2019). July has the smallest rate 349 between solar radiation and water needs, which does not coincide with works in urban 350 WPN (Pardo et al., 2020a) in which low values of irradiance in December are more 351 important than water consumption. 352

353 **4.2. Energy consumption by segment**354

As an example of the application of equations (21) and (22), let us consider the data corresponding to the problem presented in (Pardo et al., 2018), where the working power for each combination of devices is represented in Table 3:

358

Combination	1	2	3	4	5	1+2	1+3	1+4
Power	5.24	5.20	5.26	5.25	5.18	8.41	8.42	8.42
Combination	1+5	2+3	2+4	2+5	3+4	3+5	4+5	
Power	8.40	8.41	8.41	8.39	8.43	8.41	8.40	

359 Table 3: Required power for the combination of each device.

As every segment injects approximately around 80-85 L/s, and the higher and the upper and lower flow rates are ($Q_{up,th}$ =194.9 l/s, $Q_{low,th}$ =152.5 l/s) (as stated above), we know that as the number of maximum simultaneous devices Q = 2 (Figure 5). In short, $Q_{low,th} = 152.5 < 2 * 80 < 194.9 = Q_{up,th}$, and it is not possible to supply three segments as we do not meet the pressure standards.

Dealing with the figures shown in Table 3, segment 5 and the combination 2-5 are the least energy requirements when we feed one or two groups of segments. In short, $\pi_{(1)} = 5.18$ and $\pi_{(0)} = 8.39$.

368

369 **4.3. Scheduling and number of PV modules calculation**

370

371 To calculate the scheduling that minimises the number of photovoltaic panels, we 372 used two irradiance models. The first is a Kasten–Czeplak model where we get A and B

373 from the irradiance data presented in (Pardo et al., 2018). Under the conditions of equal 374 sunset hour angle (ω_s) and total day-generated energy, the irradiance equation takes the 375 form:

376
$$E(t) = 0.0158997233 \cdot cos(\pi \cdot (t/12 - 1)) + 0.0051107985.$$
 (23)

This is a direct-beam method and will serve as a first approach to the result. Then, the scheduling will start and finish with the device 5 and then pass to the combination 2-5. We can fulfil other slides with any of the possibilities offered that the required power will be much fewer than the power provided by the PV panels.

381 The question now is to establish the instant of connection and disconnection of 382 these two 'extreme solutions. We solve equation (22) to calculate variable t_2 :

383
$$\frac{12}{\pi} \cdot \arccos\left(\frac{\frac{5.18}{8.39} \left(0.01590 \cdot \cos\left(\pi \cdot \left(\frac{t_2}{12} - 1\right)\right) + 0.00511\right) - 0.00511}{0.01590}\right) + t_2 - 12 = \frac{16.25}{2}$$
(24)

The solution is $t_2 = 15.23 h$ (15:14), when the power generated by the PV panels is 0.01565 W. We calculate the disconnection time for the single device combination using equation (6) and (16):

387
$$t_1 = 12 + \frac{12}{\pi} \cdot \arccos\left(\frac{\frac{5.18}{8.39} \cdot (0.01590 \cdot \cos\left(\pi \cdot \left(\frac{15.23}{12} - 1\right)\right) + 0.00511\right) - 0.00511}{0.01590}\right) = 16.89$$
(25)

Using equation (6) and the condition about the number of panels in each period,the number of panels are:

390
$$\eta = n(t_2) = \frac{8.39}{0.01565} \approx 537$$
 (26)

We can consider this result as a first approach because of the simplicity and inaccuracy of the selected irradiance model. We will calculate the second result using an irradiance function obtained through a polynomial regression over the numeric data for 394 the panel generated power. We got these numbers with Duffie and Beckman equations

395 (Duffie and Beckman, 2013; Pardo et al., 2018).

396
$$E(t) = -1.7 \cdot 10^{-19} \cdot t^5 + 7.52 \cdot 10^{-6} \cdot t^4 - 3.6 \cdot 10^{-4} \cdot t^3 + 5.64 \cdot 10^{-3} \cdot t^2 - 5.64 \cdot 10$$

$$397 -0.32 \cdot t + 0.058 (27)$$

398 Now, the equation to solve is:

399
$$E^{-1}\left(\frac{5.18}{8.39} \cdot E(t_2)\right) + t_2 = \frac{16.25}{2}$$
 (28)

400 And the solution is also $t_2 = 15:29$ (15.48h) and the available power is now 0.0146. 401 Now, we compute the disconnection time for segment 5.

402
$$E^{-1}\left(\frac{5.18}{8.39} \cdot E(15.23)\right) = 16:38 (16.63h)$$
 (29)

403 And the optimum number of panels is:

404
$$\eta = n(t_2) = \frac{8.39}{0.0146} \approx 577$$
 (30)

405 Optimum scheduling for the polynomial irradiance is displayed in Table 4. We may
406 find that we deliver the same water to plots for every segment (irrigation time for every
407 segment is 3:15 (3.25h)).

Devices	Connection	Disconnection	Devices	Connection	Disconnection
5	7:21	7:57	1+4	12:00	12:50
2	7:57	8:31	3+4	12:50	13:39
2+5	8:31	9:34	1+3	13:39	14:28
1+4	9:34	10:23	2+5	14:28	15:31
3+4	10:23	11:12	2	15:31	16:05
1+3	11:12	12:00	5	16:05	16:39

408

Table 4: Required power for the combination of each device.

409

410 **4.4.** Discussion

Converting direct-drive pumping systems (on-grid) into standalone direct pumping photovoltaic system without dealing with the seasonal fluctuation of energy production may contribute to inaccuracies and operation issues. In this analytical procedure, the large-water use is summer is more energy-hungry than the increase in energy production. In other words, this PIN is more sensitive to water consumption than by energy production. We must calculate this for every future case.

417 The scheduling problem produces better results than those obtained before as we 418 cut down the amount of PV modules (537 and 577) for two different irradiation models. 419 But the key advantage here is not that one, but the quick response of the tool developed 420 to solve this new non-linear equation problem. Authors are aware of the practical 421 restraints indicated here (hydraulics and resource availability) as well as the future 422 functional conditions that may come out at the installation stage. Authors would like to 423 use this tool to consider segments change (in number and water consumption) for some 424 other rigid rotation predetermined scheduled.

425

To sum up, Table 5 shows the results got solving the scheduling problem.

Irradiance	Trigonometric	Polynomic
<i>t</i> ₍₋₁₎	16:53	16:38
<i>t</i> ₍₋₂₎	15:14	15:29
η	537	577

426	Table 5: Required power for the combination of each device.
427	
428 429	5. CONCLUSION The sizing of photovoltaic supplier systems is a problem of paramount importance,
430	and if PV is the primary energy source, this point becomes crucial. When the devices
431	(hydrants or units) allow flexibility for connection and disconnection time but maintaining
432	the total consumed energy, we can plan the problem as a scheduling problem. We reduce
433	the problem to a frontier problem where the solution corresponds to the lower power
434	supply curve that includes all the consumption vertexes on the energy-time
435	representation of the best working plan.
436	The presented method proposes a numeric algorithm solving of a non-linear
437	equation. It is an advance as the genetic algorithm does not guarantee to have the real
438	smallest size for the system.
439	This issue bears a direct use in pressurised irrigation networks as utility managers
440	can adjust water and energy needs. They can deliver water to crops at every moment of
441	the day. We develop a tool to solve this scheduling problem (Pardo et al., 2020b) using a
442	genetic algorithm, and the result was very time-consuming. Here, we converted this
443	problem into a non-linear equation problem.
444	But we must recognize several aspects to apply the method to an actual case. First,
445	the accuracy of the results at earlier and later hours depends on the adopted clear sky
446	models for low solar elevation angles. The effect of clouds on the effective irradiance is a
447	complex question because of its stochastic nature. A question opens at this point:

 $\,$ Including confidence intervals on irradiance curves, and then in the design of PV $\,$

- 449 installation. The results correspond to the most optimistic configuration to the power
- 450 supply, an object that can be unreal, a probabilistic analysis to examine the confidence
- 451 interval of the result might be regarded.

452

453 **AUTHOR'S CONTRIBUTIONS**

454

- 455 All authors contributed equally to this work.
- 456

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461 DATA AVAILABILITY STATEMENT

462

463 AIP Publishing believes that all datasets underlying the conclusions of the paper should 464 be available to readers. We encourage authors to deposit their datasets in publicly 465 available repositories (where available and appropriate) or present them in the main 466 manuscript. All research articles must include a data availability statement informing 467 where the data can be found. By data, we mean the minimal dataset that would be 468 necessary to interpret, replicate and build upon the findings reported in the article. The data that support the findings of this study are available from the corresponding author 469 470 upon reasonable request.

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